(Following Paper ID and Roll No. to be filled in your Answer Book)

PAPER ID: 2488

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Roll No.		·			4		

B.Tech.

(SEMESTER-VI) THEORY EXAMINATION, 2012-13

DIGITAL SIGNAL PROCESSING

Time: 3 Hours]

[Total Marks: 100

SECTION - A

1. Attempt all question parts:

- $10\times 2=20$
- (a) Determine the direct form realization of the linear phase filter given by $h(n) = \{1, 2, 3, 4, 3, 2, 1\}.$
- (b) Find whether the digital filter given by the impulse response $h(n) = \{1 202 1\}$ is linear phase or not. Prove your answer.
- (c) "A stable system is always causal". Justify the statement.
- (d) Compute the N-point DFT of the signal $x(n) = a^n$ for $0 \le n \le N 1$
- (e) Compare between linear convolution and circular convolution.
- (f) If $x(n) = \delta(n) + \delta(n-1) + \delta(n-2)$, determine $X(e^{j\omega})$.
- (g) Discuss the properties of Chebyshev polynomial.
- (h) Explain the term "Group delay" with respect to filters.
- (i) Draw the butterfly diagram for N = 8.
- (j) State the condition for design of stable digital filter from stable analog filter.

SECTION – B

2. Attempt any three question parts:

 $3 \times 10 = 30$

- (a) Consider an FIR filter described by the system function $H(z) = 1 + 2.88z^{-1} + 3.4048z^{-2} + 1.74z^{-3} + 0.4z^{-4}$
 - (i) Sketch the lattice realization of the filter.
 - (ii) Is the system minimum phase

- (b) Find the linear convolution of sequences using the overlap add method $x(n) = \{1, 2, 0, 3, 4, 1, 0, 1, 2, 3, 2, 1\}$ and $h(n) = \{4, 1, 2\}$
- (c) Convert the analog filter with the system function

$$H_a(s) = \frac{s + 0.2}{(s + 0.2)^2 + 9}$$

into a digital IIR filter using impulse invariant technique. Assume T = 1s.

(d) Determine the cascade and parallel form realization for an LTI system described by the difference equation

$$y(n) = \frac{1}{4}y(n-2) + x(n)$$

(e) Given that $x(n) = \{2, 2, 2, 2, 1, 1, 1, 1\}$. Compute 8 point FFT using decimation-in-time method.

SECTION - C

Attempt all questions:

 $5 \times 10 = 50$

3. Attempt any two parts:

 $2 \times 5 = 10$

- (a) An FIR filter is described by the difference equation y(n) = x(n) x(n 10). Compute and sketch its Fourier Transform magnitude and phase spectrum.
- (b) Define Discrete Time Fourier Transform (DTFT) of a sequence x(n). Determine DTFT for $\cos \omega_0 n$ and $\sin \omega_0 n$.
- (c) Obtain the direct form II structure for the system given by the transfer function $y(n) = \frac{3}{4} y(n-1) \frac{1}{8} y(n-2) + x(n) + \frac{1}{3} x(n-1)$

4. Attempt any one part:

 $1 \times 10 = 10$

(a) The desired frequency response of a low pass filter is given by

$$H_{d}(e^{j\omega}) = \begin{cases} e^{-j\omega}, |\omega| \leq \frac{\pi}{4} \\ 0, \text{ otherwise} \end{cases}$$

Design the filter using hamming window.

(b) Given an 8 point sequence x(n) = n + 1 where n = 0.1, 2, ..., 7. Develop an FFT algorithm using decimation-in-frequency (DIF) approach. Discuss its advantages in terms of savings in complex additions and multiplication.

5. Attempt any one part:

 $1 \times 10 = 10$

(a) The frequency response of an ideal bandpass filter is given by

$$H(\omega) = \begin{cases} 0 & |\omega| \le \frac{\pi}{8} \\ 1 & \frac{\pi}{8} < |\omega| < \frac{3\pi}{8} \\ 0 & \frac{3\pi}{8} \le |\omega| \le \pi \end{cases}$$

Determine its impulse response.

(b) Perform the convolution of the following two sequences h(n) and x(n)

$$h(n) = \begin{cases} \left(\frac{1}{2}\right)^n & 0 \le n \le 2\\ 0 & \text{otherwise} \end{cases}$$
 and
$$x(n) = \delta(n) + \delta(n-1) + 4\delta(n-2)$$

6. Attempt any one part:

 $1 \times 10 = 10$

- (a) Derive the condition of an FIR filter to give linear phase response. Also, find the frequency response of a given FIR filter, if the number of samples, N, in its impulse response h(n) is odd.
- (b) Using bilinear transformation, design a Butterworth low pass filter to meet the following specifications:

$$\begin{split} 0.8 & \leq |H(e^{j\omega})| \leq 1 & 0 \leq |\omega| \leq 0.2\pi \\ |H(e^{j\omega})| & \leq 0.2 & 0.6\pi \leq |\omega| \leq \pi \end{split}$$

7. Attempt any two parts:

 $2 \times 5 = 10$

- (a) Derive the frequency transformation for converting a prototype digital low pass filter into a digital highpass filter.
- (b) Show that the zeros of a linear phase FIR filter occurs at reciprocal location.
- (c) Show that the output data is in bit reversed order for the decimation in frequency algorithm for N = 8.